

Consistency of robust portfolio estimates.

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Outline.

1. Traditional portfolio optimization.

1.1 Markowitz optimization

1.2 Estimation risk

1.3 Consistency

2. Robust portfolio optimization.

2.1 Robust counterparts

2.2 Estimation risk

2.3 Consistency

Portfolio optimization. Traditional Markowitz model.

Markowitz framework.

- Set of feasible portfolios $X \subset \mathbb{R}^n$ (convex, compact), i.e. $x^T \mathbf{1} = 1$ for $x \in X$.
- Expected asset returns $\mathbf{r} = \mathbf{E}[R]$.
- Covariance matrix of asset returns $\mathbf{C} = \mathbf{Var}[R]$.
- Expected portfolio return $x^T \mathbf{r}$.
- Volatility (= risk) of portfolio $\sqrt{x^T \mathbf{C} x}$.

Markowitz portfolio optimization problem.

$$\min_{x \in X} (1 - \lambda) \sqrt{x^T \mathbf{C} x} + \lambda (-x^T \mathbf{r}) \quad (\text{PO})$$

- Risk-return trade-off parameter λ (with $0 \leq \lambda \leq 1$).
- Optimal portfolio x^* depends on \mathbf{r} and \mathbf{C} , i.e. $x^* = x_{\mathbf{r}, \mathbf{C}}^*$.

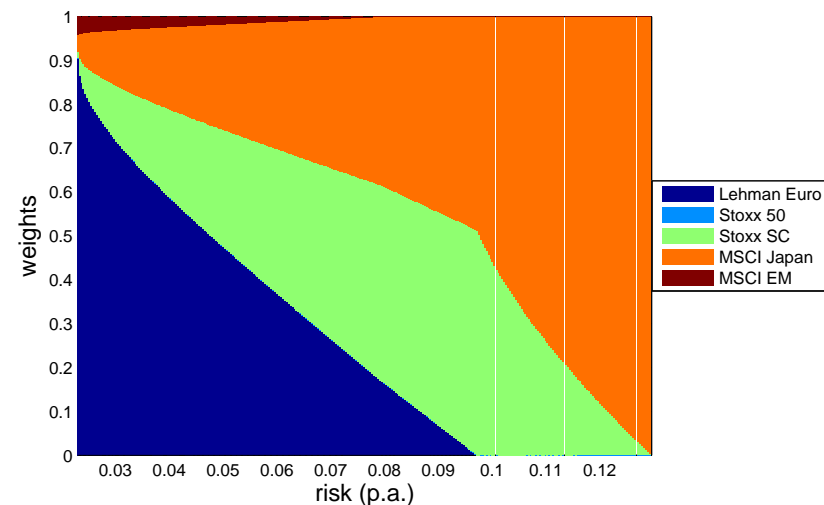
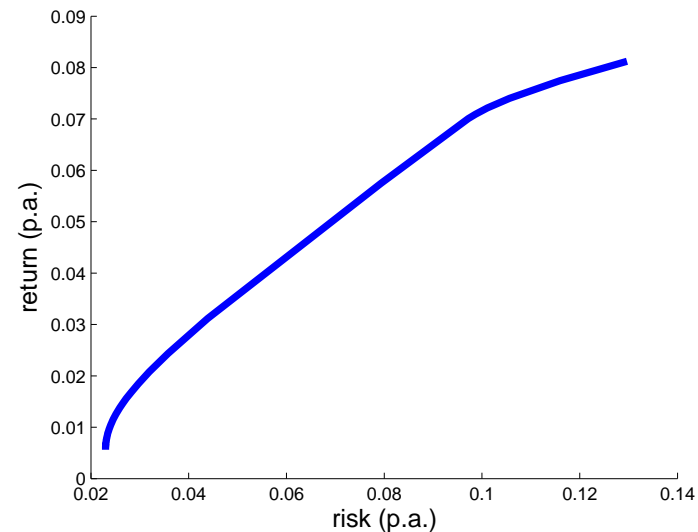
Portfolio optimization. Traditional Markowitz model.

Illustration.

- The trade-off parameter λ is used to trace the **efficient frontier**.
- For $\lambda = 0$ we get the **minimum variance portfolio**.
- For $\lambda = 1$ we get the **maximum return portfolio**.

Remark.

- The calculation of the efficient frontier can also be formulated as a vector optimization problem.



Portfolio optimization. Traditional Markowitz model.

Market model.

- Elliptical model for asset returns $R \sim \mathcal{E}(r, C, \varphi)$ with density generator φ .
- Elliptical models contain the multivariate normal distribution as a special case.
- Elliptical models are still compatible with preference/utility theory.

Estimation of the input parameters r and C .

- We assume that S historical return realizations R_1, \dots, R_S (iid) are given.
- In the traditional Markowitz framework, maximum likelihood estimators for r and C are used to get the input data for (PO)

$$\hat{\mu}_S^{ML} = \frac{1}{S} \sum_{s=1}^S R_s, \quad \hat{\Sigma}_S^{ML} = \frac{1}{S} \sum_{s=1}^S (R_s - \hat{\mu}_S^{ML})(R_s - \hat{\mu}_S^{ML})^T$$

- Other approaches like Bayes estimator, Black-Litterman estimators or robust estimators are also used frequently.

Portfolio optimization.
Estimation risk.

True and actual efficient portfolio.

- For market parameters (r, C) , the **true efficient portfolio** is $x_{r,C}^*$.
- As only estimators (μ, Σ) are available, the **actual efficient portfolio** is $x_{\mu,\Sigma}^*$.
- The actual portfolio can be seen as an estimator for the true efficient portfolio.

True, actual and predicted risk and return.

	true	actual	predicted
expected return	$x_{r,C}^{*T} r$	$x_{\mu,\Sigma}^{*T} r$	$x_{\mu,\Sigma}^{*T} \mu$
risk	$\sqrt{x_{r,C}^{*T} C x_{r,C}^*}$	$\sqrt{x_{\mu,\Sigma}^{*T} C x_{\mu,\Sigma}^*}$	$\sqrt{x_{\mu,\Sigma}^{*T} \Sigma x_{\mu,\Sigma}^*}$

Estimation risk.

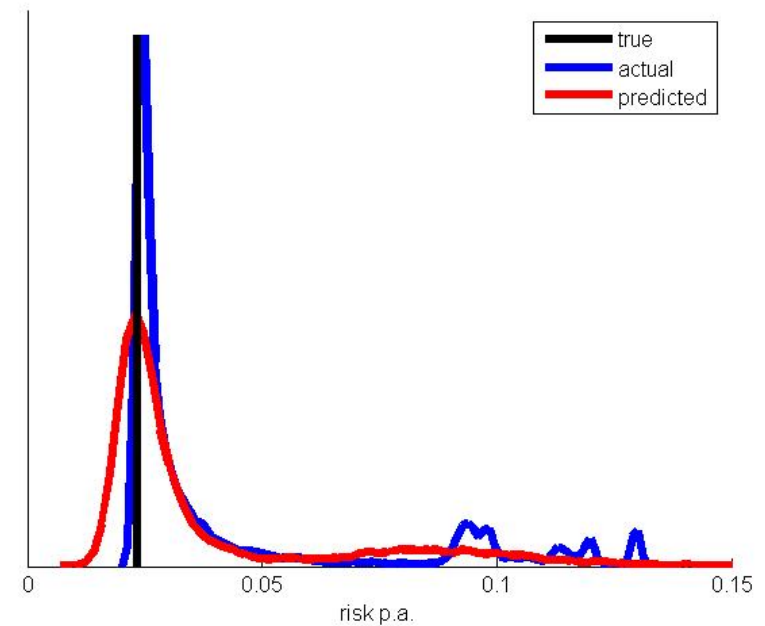
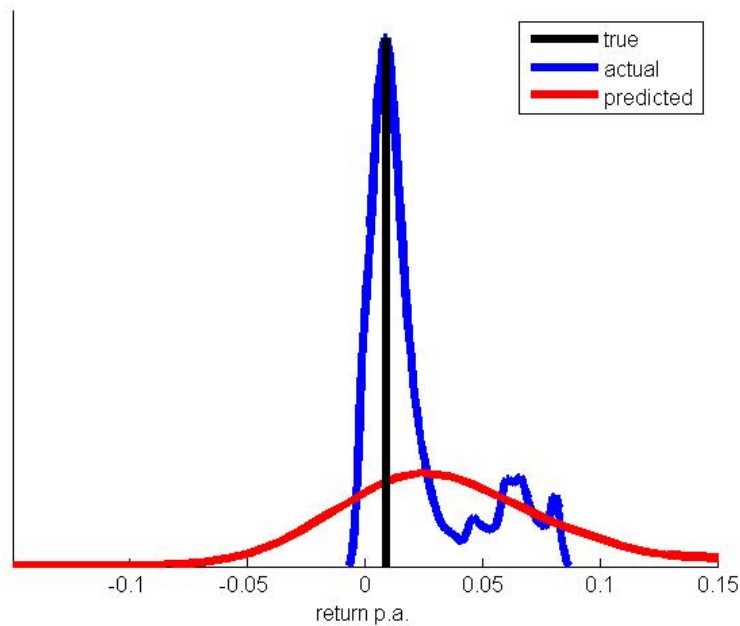
- Estimation risk = true quantity – predicted quantity.

How big is this estimation risk?

Portfolio optimization. Estimation risk.

Example.

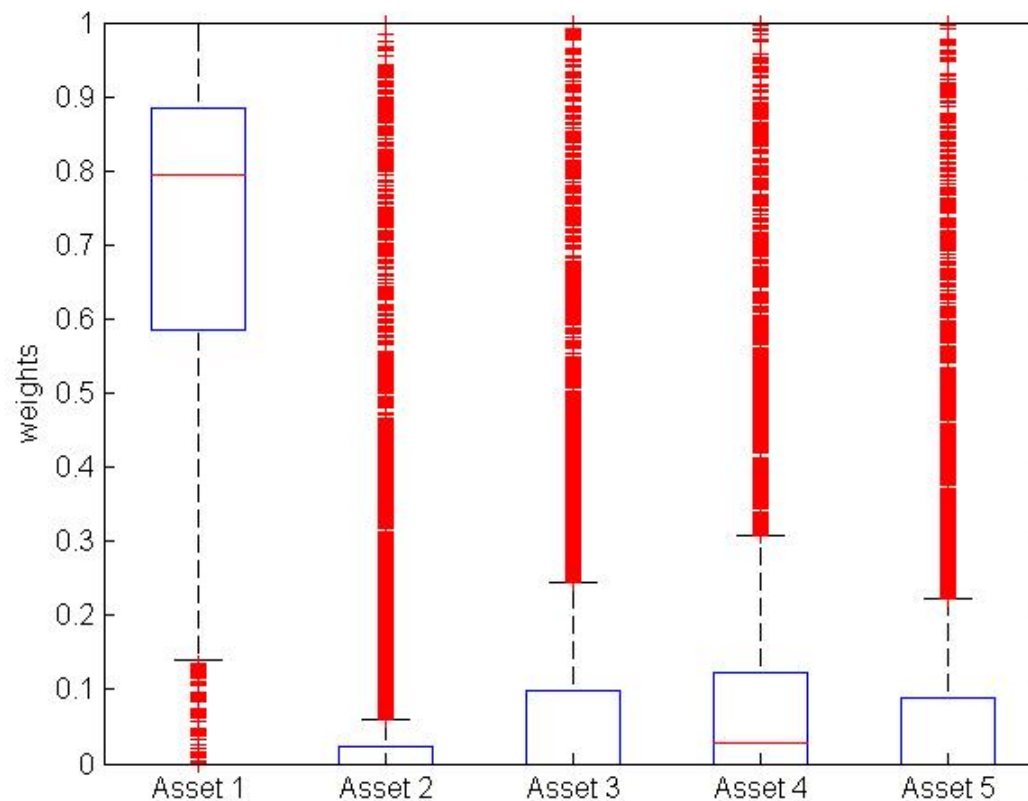
- The actual risk and return figures deviate from the optimal ones.
- The predicted return figures show significant deviations.



Portfolio optimization. Estimation risk.

Example (cont'd).

- The weights vary strongly, sometimes even dramatically (i.e. the outliers).



Portfolio optimization. Estimation risk.

Brief summary of known results.

- Estimation risk was an active research topic from late 70's until early 90's.
- Most popular papers: Barry, Jobson/Korkie, Bawa/Brown/Klein, ...
- Main (empirical) result: optimal portfolios strongly depend on input r and C .

Is estimation risk vanishing with increasing sample size S ?

- Jobson/Korkie: if $S > 200$, estimation risk can be neglected.
- Random matrix theory: the ratio of S to n must be large.
- The appropriate notion from statistics is **consistency**.
- An even better property allowing for some quantitative estimate is **asymptotic normality**.

Portfolio optimization. Consistency.

Definition.

A point estimator $\mathcal{Q}_{p,S}$ for a parameter p based on a sample of size S is called

- **unbiased**, if $\mathbf{E}[\mathcal{Q}_{p,S}] = p$,
- **strongly consistent**, if $\mathbf{P}\left[\lim_{S \rightarrow \infty} \mathcal{Q}_{p,S} = p\right] = 1$
(convergence almost surely),
- **(weakly) consistent**, if $\lim_{S \rightarrow \infty} \mathbf{P}\left[|\mathcal{Q}_{p,S} - p| > \varepsilon\right] = 0$
(convergence in probability).

Remarks.

- Almost sure convergence and convergence in probability remain valid after continuous transformations.
- The portfolio estimator is in general biased, even if unbiased estimators for the input data are applied.

Portfolio optimization. Consistency.

Main results concerning consistency and asymptotic normality.

- Jobson/Korkie (1980): The optimal solution x^* is consistent and asymptotically normal, if R is normal. This result is derived from an analytical solution for x^* based on a special structure of X .
- Mori (2004): Extension to the case that X includes linear equalities.
- Lauprete (2002): Similar results to Mori, but with R being elliptic and a slightly different optimization problem.
- Jobson/Korkie (1980s) also characterized the distribution of x^* for small S .
- Okhrin/Schmid (2006): Extension of the Jobson/Korkie results to elliptical distributions.

Consistency for a general set X and R elliptic is still missing!

Portfolio optimization. Consistency.

Theorem.

Assume that the following convex optimization problem (with convex, compact X)

$$\begin{aligned} \min_{x \in X} \quad & f(x, u) \\ \text{s.t.} \quad & g(x, u) \leq 0 \end{aligned}$$

has an unique optimal solution $x^*(u)$ in a neighborhood of \hat{u} . Then x^* is continuous at \hat{u} , if

- the objective f and the constraint g are continuous, and either
- the constraint g is not depending on u , or
- there exists a Slater point for \hat{u} , i.e. $\exists \hat{x} \in X$ such that $g(\hat{x}, \hat{u}) < 0$.

Corollary.

The optimal portfolio $x_{r,C}^*$ is continuously depending on (r, C) .

Portfolio optimization. Consistency.

Theorem (Schöttle, Werner – 2006).

Let μ and Σ be consistent estimators for r and C . Then the optimal solution $x_{\mu, \Sigma}^*$ is also a consistent estimator for $x_{r, C}^*$.

Remarks.

- The above result generalizes all existing results.
- The key to consistency is continuity of the solution of (PO) with respect to the parameters.
- Thus, the result can easily be generalized to the case that X depends (Hausdorff) continuously on r and C .
- Uniqueness of x^* follows from the strict convexity of $x \mapsto \sqrt{x^T C x}$ on X .
- For asymptotic normality, we need differentiability of x^* with respect to the input parameters r and C .

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2. **Robust portfolio optimization.**
 - 2.1 Robust counterparts
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Robust portfolio optimization. Robust counterpart.

The need for robustification.

- Although stability is given from a mathematical point of view, dependence on the parameters is still unsatisfactorily high.
- In the last 15 years, several approaches were introduced to reduce the estimation error while keeping efficiency as high as possible.
 - Usage of more robust estimators (shrinkage, M-estimators, ...)
 - Michaud's resampling,
 - Stochastic optimization and scenario optimization,
 - **Robust counterpart.**
- Several empirical studies support the usage of robust approaches for small sample sizes S .
- Robustification usually decreases the estimation variance, but at the same time introduces a bias in the estimation.

Robust portfolio optimization.
Robust counterpart.

The robust counterpart.

Based on an uncertainty set U the robust counterpart is defined as

$$\begin{array}{ll} \min_{x \in X} & f(x, u) \\ \text{s.t.} & g(x, u) \leq 0 \end{array} \qquad \begin{array}{ll} \min_{x \in X} & \max_{u \in U} f(x, u) \\ \text{s.t.} & \max_{u \in U} g(x, u) \leq 0. \end{array}$$

Setting $F(x, U) := \max_{u \in U} f(x, u)$ and $G(x, U) := \max_{u \in U} g(x, u)$ this becomes

$$\begin{array}{ll} \min_{x \in X} & F(x, U) \\ \text{s.t.} & G(x, U) \leq 0 \end{array}$$

Robust portfolio optimization

$$\min_{x \in X} \max_{(\mu, \Sigma) \in U} (1 - \lambda) \sqrt{x^T \Sigma x} + \lambda (-x^T \mu) \quad (\text{RO})$$

Robust portfolio optimization.
Robust counterpart.

Important facts about the robust counterpart (Schöttle, Werner – 2006).

- It holds: f, g convex in $x \implies F, G$ convex in x .
- It holds: f, g strictly convex on $X \implies F, G$ strictly convex on X .
- It holds: f, g continuous in $u \implies F, G$ continuous in U .
- Continuity in U is always understood in the Hausdorff sense.
- If the original problem has a Slater point and U is small enough, then the robust counterpart also possesses a Slater point.

Interpretation.

- The robust counterpart inherits all nice properties from the original problem.
- Instead of a real parameter $u \in \mathbb{R}^d$ a set $U \in 2^{\mathbb{R}^d}$ becomes the parameter.

Robust portfolio optimization. Robust counterpart.

Choice of the uncertainty set U .

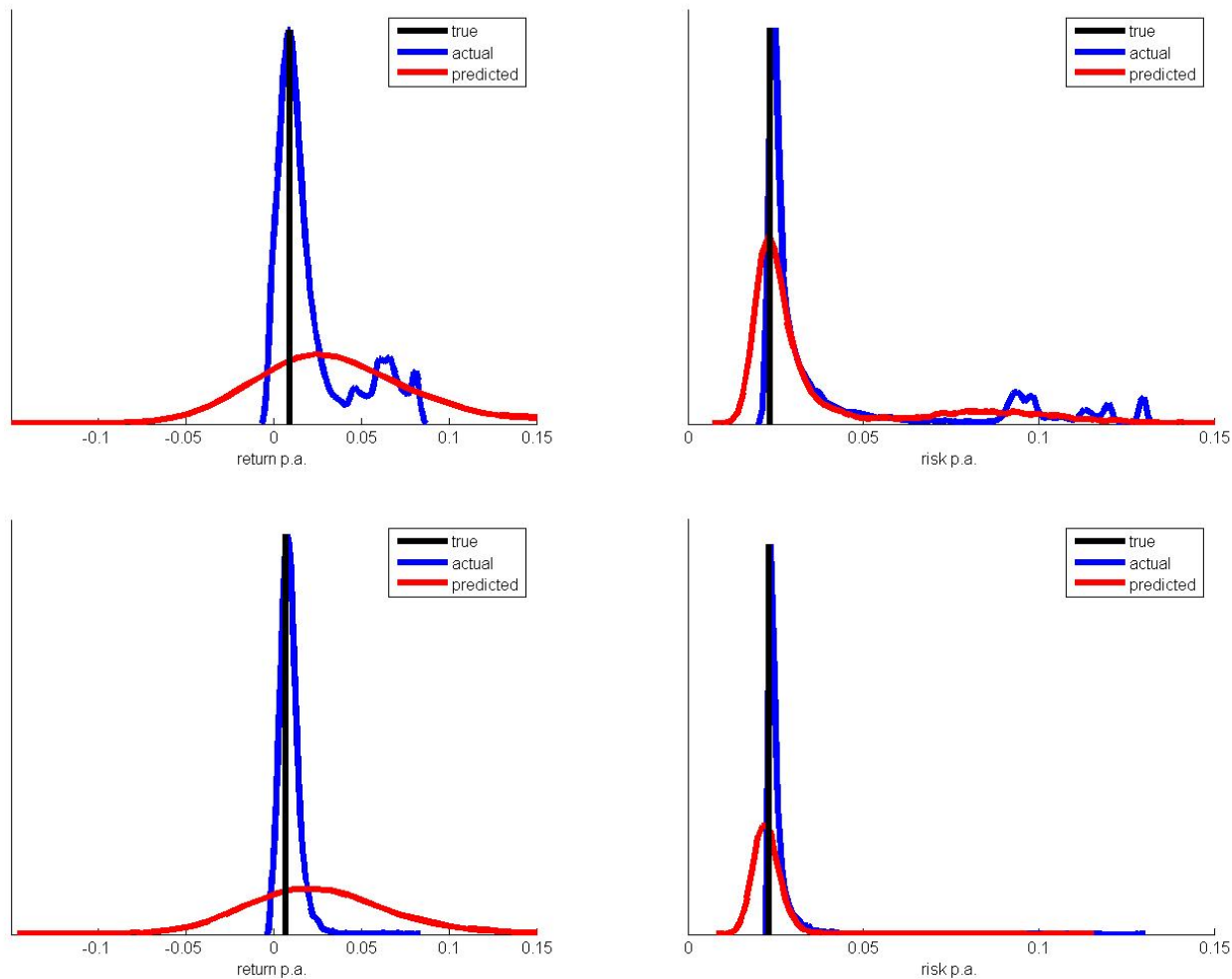
- Most obvious choice for U is the (joint) confidence ellipsoid centered at the estimates $\hat{\mu}$ and $\hat{\Sigma}$.
- In the special case of normally distributed returns and maximum likelihood estimators, the uncertainty set can be explicitly described by

$$U = \{(\mu, \Sigma) \mid S(\mu - \hat{\mu})^T \hat{\Sigma}^{-1}(\mu - \hat{\mu}) + \frac{S-1}{2} \|\hat{\Sigma}^{-\frac{1}{2}}(\Sigma - \hat{\Sigma})\hat{\Sigma}^{-\frac{1}{2}}\|_{\text{tr}}^2 \leq \delta^2\}.$$

- Generalizations to elliptical distributions and other estimators are in general possible, but may involve numerical procedures (i.e. numerical integration, etc.).
- Other – mainly polyhedral – uncertainty sets have also been investigated in the literature.
- For small S the shape of U plays an important role, but for large S , only the size of U matters.

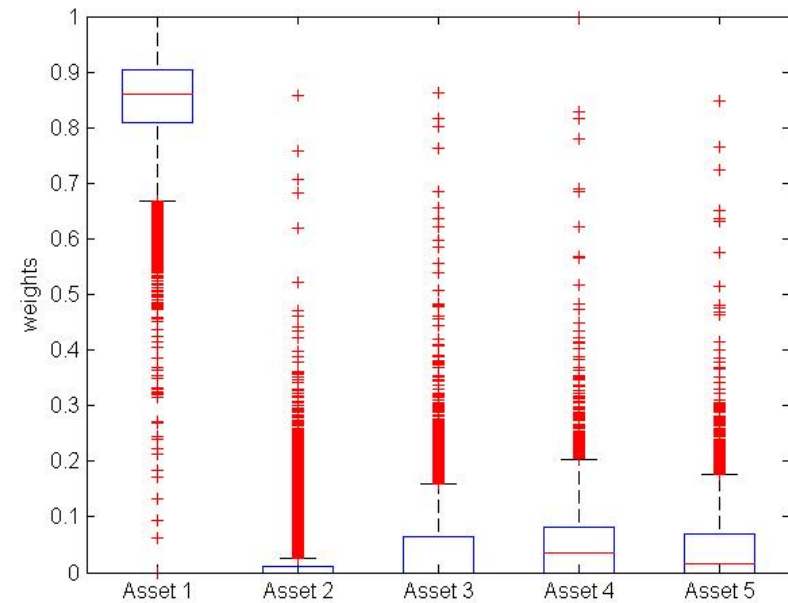
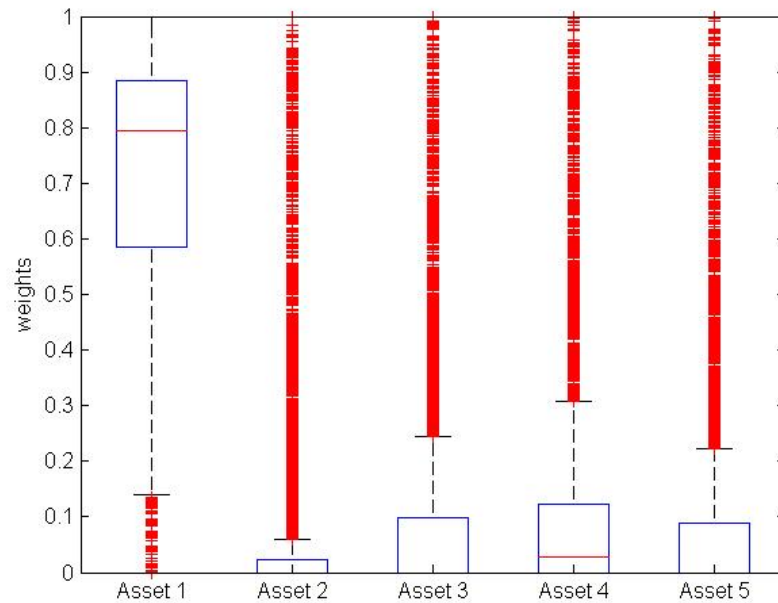
Robust portfolio optimization. Estimation risk.

Robustification reduces estimation risk.



Robust portfolio optimization.
Estimation risk.

Robustified portfolios are more stable.



- Stability in weights comes with a small bias in portfolio weights.

Robust portfolio optimization. Consistent uncertainty sets.

Definition.

An uncertainty set U is called **strongly consistent** for the pair (r, C) if

$$H_d(U, \{(r, C)\}) \rightarrow 0 \quad \text{almost surely for } S \rightarrow \infty,$$

with $H_d(A, B)$ denoting the Hausdorff distance between the sets A and B .

Remarks.

- (Weak) consistency can be defined analogously (by convergence in probability).
- Consistent uncertainty sets are the natural analogon to consistent point estimates.
- Consistent uncertainty sets shrink to the real data.
- The uncertainty set from the previous example is strongly consistent.

Portfolio optimization. Consistency.

Theorem.

Assume that the robust counterpart

$$\begin{aligned} \min_{x \in X} \quad & F(x, U) \\ \text{s.t.} \quad & G(x, U) \leq 0 \end{aligned}$$

has a unique optimal solution $x^*(\hat{U})$ in a neighborhood of \hat{U} . Then x^* is continuous at \hat{U} , if

- the objective F and the constraint G are continuous, and either
- the constraint G is not depending on U , or
- there exists a Slater point for \hat{U} .

Remark.

Not surprisingly, this is the same result as for the original problem.

Robust portfolio optimization. Consistency.

Theorem (Schöttle, Werner – 2006).

Let U be a consistent uncertainty set for (r, C) . Then the optimal solution x_U^* is a consistent estimator for $x_{r,C}^*$.

Remarks.

- The above result generalizes the result of the traditional framework.
- The key to consistency is continuity of the solution with respect to the uncertainty set.
- Thus, the result can be easily generalized to the case that X depends (Hausdorff) continuously on r and C .
- Uniqueness of x^* follows from the strict convexity of $x \mapsto \sqrt{x^T C x}$ on X .
- What about asymptotic normality?

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2. **Resampled portfolio optimization.**
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Resampled portfolio optimization.
Resampled asset returns and bootstrapped estimators.

Resampled asset returns.

- Fix resampling parameters $(r_{res}, C_{res}, \psi_{res})$ for **resampled asset returns**

$$R_{res} \sim \mathcal{E}(r_{res}, C_{res}, \psi_{res}).$$

The bootstrapped estimator distribution.

- Take S samples of R_{res} and use any **continuous and consistent estimator** to obtain μ_{res} and Σ_{res} .
- This induces the **bootstrapped distribution** \mathcal{B}_S for μ_{res} and Σ_{res} :

$$(\mu_{res}, \Sigma_{res}) \sim \mathcal{B}_S(r_{res}, C_{res}, \psi_{res}).$$

Example.

- In Michaud's original setting: $R_{res} \sim \mathcal{N}(r_{res}, C_{res})$.
- Using the maximum likelihood estimators, the bootstrapped distribution is analytically given: $\mathcal{B}_S(r_{res}, C_{res}, \psi_{res}) = \mathcal{N}(r_{res}, \frac{1}{S}C_{res}) \otimes \mathcal{W}(\frac{1}{S}C_{res}, S - 1)$.

Resampled portfolio optimization.
Resampled portfolios.

Resampled portfolios.

- Plug in μ_{res} and Σ_{res} in (PO) to obtain $x_{\mu_{res}, \Sigma_{res}}^*$.
- Based on the distribution of the bootstrapped x^* the **resampled portfolio** is defined as:

$$y_{r_{res}, C_{res}}^* := y_{r_{res}, C_{res}, S, \psi_{res}}^* := \mathbf{E}[x_{\mu_{res}, \Sigma_{res}}^*] \quad \text{with } (\mu_{res}, \Sigma_{res}) \sim \mathcal{B}_S(r_{res}, C_{res}, \psi_{res})$$

Resampled portfolios – algorithmic view.

1. Fix resampling parameters and resample S asset returns.
2. Calculate estimators for risk and return.
3. Plug them into the portfolio problem and compute optimal portfolios.
4. Repeat the above K times and take the average of all these portfolios.

Where do the resampling parameters (r_{res}, C_{res}) come from?

Resampled portfolio optimization. Resampled portfolios.

Important facts about resampled portfolios.

- For small S , the choice of ψ_{res} is important. For large S , the density generator can be chosen arbitrarily.
- The resampling parameters r_{res} and C_{res} are estimated from the historical sample R_1, \dots, R_S .
- The estimators which are used to derive r_{res} and C_{res} are used for the estimation of the bootstrapped estimators μ_{res} and Σ_{res} as well.

Continuity properties.

- For fixed S , the resampled portfolio is continuous in the resampling parameters:

$$y_{r_k, C_k, S, \psi_{res}}^* \rightarrow y_{\bar{r}, \bar{C}, S, \psi_{res}}^* \quad \text{for } r_k \rightarrow \bar{r}, C_k \rightarrow \bar{C}.$$

- For fixed resampling parameters, it holds independent of ψ_{res} :

$$y_{r_{res}, C_{res}, S, \psi_{res}}^* \rightarrow x_{r_{res}, C_{res}}^* \quad \text{for } S \rightarrow \infty.$$

Resampled portfolio optimization. Consistency.

Theorem (Schöttle, Werner – 2006).

Let r_{res} and C_{res} be derived by continuous and consistent estimators for r and C .
Then the resampled portfolio $y_{r_{res}, C_{res}}^*$ is a consistent estimator for $x_{r, C}^*$, independent of the choice of ψ_{res} .

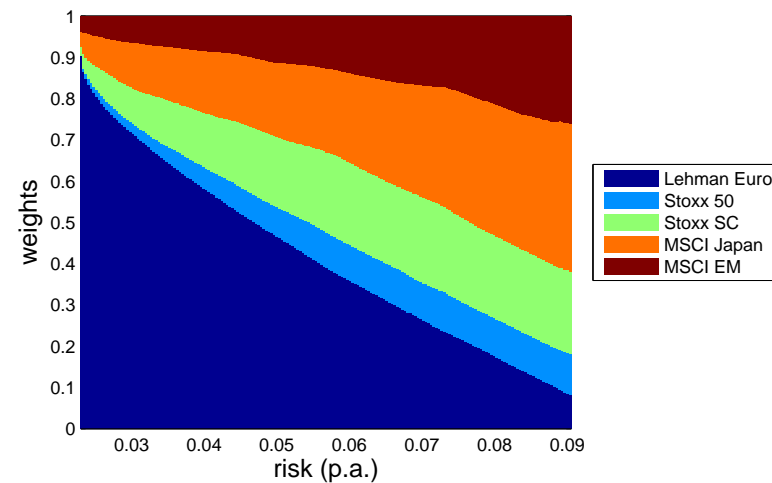
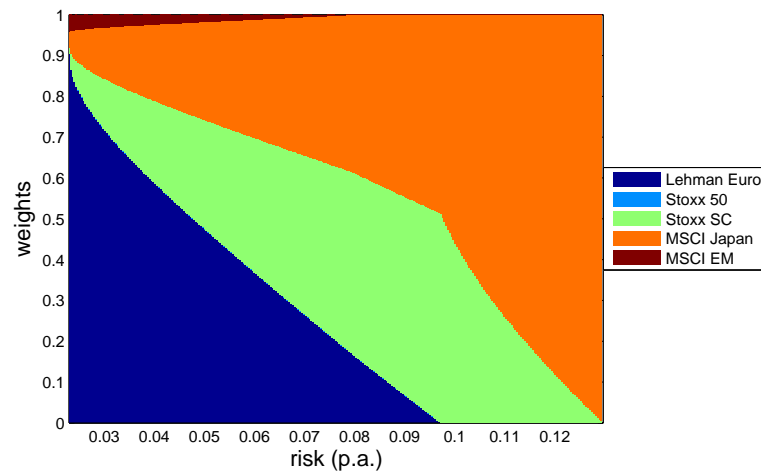
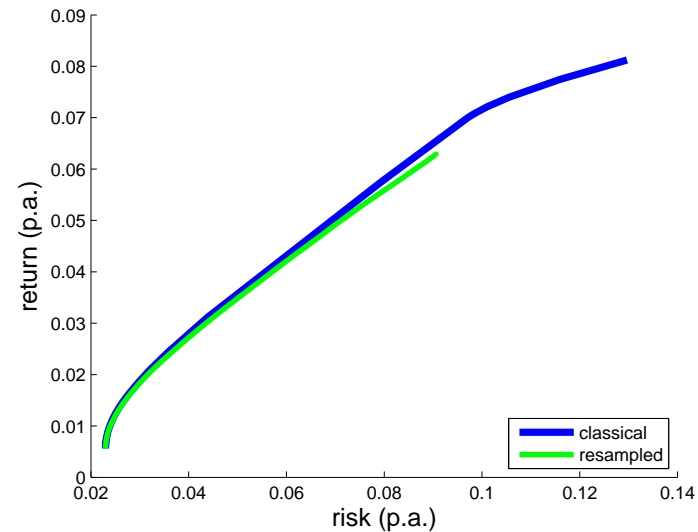
Remarks.

- The key to consistency is again continuity of the solution of (PO) with respect to the uncertain parameters.
- Thus, the result can be easily generalized to the case that X depends (Hausdorff) continuously on r and C .
- Compactness of X is crucial for the above continuity result.
- What about asymptotic normality?

Resampled portfolio optimization. Costs and benefits of resampling.

Observations.

- The resampled frontier is close to the original frontier.
- The resampled frontier is shorter than the original frontier.
- The resampled portfolio allocations look more reasonable.



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HOLDING